

Group Theory
Week #4, Lecture #16

I Generating sets

Recall a cyclic group G is generated by a single element:

$$G = \langle a \rangle = \{ e, a, a^2, \dots, a^n, \dots \}$$

($G \cong \mathbb{Z}_n$ for some n , or $G \cong \mathbb{Z}$)

Other groups need 2 or more generators.

Def Let $S \subseteq G$ be a subset of a group G . The subgroup of G generated by S is:

$$\langle S \rangle := \{ g \in G : g = x_1^{\pm 1} \dots x_n^{\pm 1}, \text{ for some } x_i \in S \}$$

note: $S \subseteq \langle S \rangle$

all possible finite products of elements in S and their inverses

Check that $\langle S \rangle$ is indeed a subgroup of G :

let $g = x_1 \dots x_n \in \langle S \rangle$. Then $gh = (x_1 \dots x_n)(y_1 \dots y_m)$
 $h = y_1 \dots y_m \in \langle S \rangle$
 $= x_1 \dots x_n y_1 \dots y_m \in \langle S \rangle$

where $x_i, y_j \in S \rightarrow y_j^{-1} \in S$

• $e \in \langle S \rangle$ (the empty product)

• $h^{-1} = y_m^{-1} \dots y_1^{-1} \in S$ ✓

Remark 1 If G is written additively $= G = (G, +, 0)$

(something we usually do if G is abelian) — then

$$\begin{aligned} \langle S \rangle &= \{ g \in G \mid g = \pm x_1 \pm \dots \pm x_n \text{ for } x_i \in S \} \\ &= \{ g \in G \mid g = c_1 x_1 + \dots + c_n x_n \quad \begin{matrix} x_i \in S \\ c_i \neq 0 \end{matrix} \} \\ &= \{ g \in G \mid g = k_1 x_1 + \dots + k_n x_n, \quad \begin{matrix} x_i \in S \\ k_i \in \mathbb{Z} \end{matrix} \} \end{aligned}$$

This is similar with the definition of a vector subspace

all linear combinations of elements in S inside a vector space V

Remark 2 $\langle S \rangle$ is the smallest subgroup of G containing S . In fact:

$$\langle S \rangle = \bigcap_{\substack{H \in \mathcal{G} \\ S \subseteq H}} H$$

Remark 3. If $G = \langle S \rangle$, we call S a generating set for G , and the elements of S are called generators of G .

G is a finitely generated group if $G = \langle x_1, \dots, x_n \rangle$ for some $x_i \in G$.

Examples

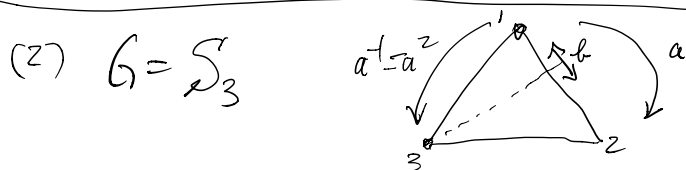
(1) $G = \mathbb{Z}^2 = \mathbb{Z} \times \mathbb{Z}$ is generated by $x = (1, 0)$ and $y = (0, 1)$
(much the same as \mathbb{R}^2 is - generated by x & y)

i.e.: $\mathbb{Z}^2 = \langle x, y \rangle$

in other words, every pair $(m, n) \in \mathbb{Z}^2$ can be written as

$$(m, n) = \pm(1, 0) \pm \dots \pm (1, 0) \pm (0, 1) \pm \dots \pm (0, 1)$$

eg: $(5, -3) = \underbrace{(1, 0) + \dots + (1, 0)}_5 - \underbrace{(0, 1) - \dots - (0, 1)}_3$



Let $a = 120^\circ$ rotation $= \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}$

$b =$ reflection in dashed axis $= \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix}$

Then G is generated by a and b :

$$S_3 = \left\{ \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix} \right\}$$

$e \quad a \quad a^2 \quad b \quad ba \quad ba^2$

$$= \langle \{a, b\} \rangle$$

In fact, S_3 has presentation:

$$S_3 = \langle a, b \mid \underbrace{a^3=e, b^2=e, ba=a^2b}_{\text{relations in the group}} \rangle$$

↑
generators

$$= \underbrace{\mathbb{Z}_3}_{\langle a \rangle} \amalg \underbrace{\mathbb{Z}_3}_{\{b, ba, ba^2\}}$$

↑
 $\{e, a, a^2\}$

For a presentation for the dihedral group D_n (symmetries of the n -gon), see notes on web page.

II Derived subgroup and abelianization

Def Given elements x, y in a group G , their commutator is

$$\boxed{xyx^{-1}y^{-1} \in G}$$

- This is usually denoted by $[x, y]$ (or (x, y))
 - Warning: GAP uses $[x, y] = x^{-1}y^{-1}xy$
 - Note x and y commute (i.e., $xy=yx$) if and only if their commutator is the identity (i.e., $xyx^{-1}y^{-1}=e$)
- "commutator measures failure of commutativity"

Def The derived subgroup (or, the commutator subgroup) of a group G is

$$\boxed{G' = \langle \{ g \in G : g = xyx^{-1}y^{-1} \text{ for some } x, y \in G \} \rangle}$$

i.e., the set of all products of commutators in G .

Examples: (1) G abelian (or, commutative) $\Rightarrow G' = \{e\}$

(2) $G = S_3 \Rightarrow G' = \{e, a, a^2\} \cong \mathbb{Z}_3$

reason: $ba = a^2b \Rightarrow a^2 = bab^{-1} \Rightarrow a = bab^{-1}a^{-1} = [b, a]$

Proposition (1) G' is a normal subgroup of G .

(2) G/G' is abelian

(3) If $N \triangleleft G$, then:

G/N is abelian $\Leftrightarrow G' \subseteq N$

Proof (i) (a) G' is a subgroup:

• $g, h \in G' \Rightarrow g = aba^{-1}b^{-1}, h = xyx^{-1}y^{-1}$ for some $a, b, x, y \in G$
 $\Rightarrow gh = aba^{-1}b^{-1} \cdot xyx^{-1}y^{-1} \in G'$
 \triangleleft we need $\langle \dots \rangle$ here!

• $g \in G' \Rightarrow g = aba^{-1}b^{-1}, a, b \in G$
 $\Rightarrow g^{-1} = bab^{-1}a^{-1} \in G'$ (i.e., $[a, b]^{-1} = [b, a]$)

• $e = [e, e] \in G'$ ✓

(ii) G' is a normal subgroup:

$g \in G', x \in G \Rightarrow xgx^{-1}g^{-1} \in G'$ (by def of G')
 $\xrightarrow{aba^{-1}b^{-1}}$
 $\Rightarrow xgx^{-1} \in G'$ (since G' is a subgroup)
multiply by g on the right ✓

(2) G/G' abelian:

let aG' and bG' be two cosets of G' . Then (*)
 $aG' \cdot bG' \cdot (aG')^{-1} \cdot (bG')^{-1} = aG' \cdot bG' \cdot a^{-1}G' \cdot b^{-1}G'$

$$\text{since } aba^{-1}b^{-1} \in G' \xrightarrow{\quad} = aba^{-1}b^{-1} \cdot G' \xrightarrow{\quad} G'$$

(3) (\Rightarrow) If $N \triangleleft G$ & G/N is abelian, then, for $\forall a, b \in G$:

$$aba^{-1}b^{-1}N = N \quad (\text{by argument } (*))$$

$$\therefore aba^{-1}b^{-1} \in N$$

$$\therefore G' \subseteq N$$

(\Leftarrow) If $G' \subseteq N \triangleleft G$, then, by the 2nd Isomorphism (next week)

The projection $\pi: G \rightarrow G/N$

factors through a projection $\bar{\pi}: G/G' \rightarrow G/N$

Hence, since G/G' is abelian by (2), we conclude that G/N is also abelian. \square

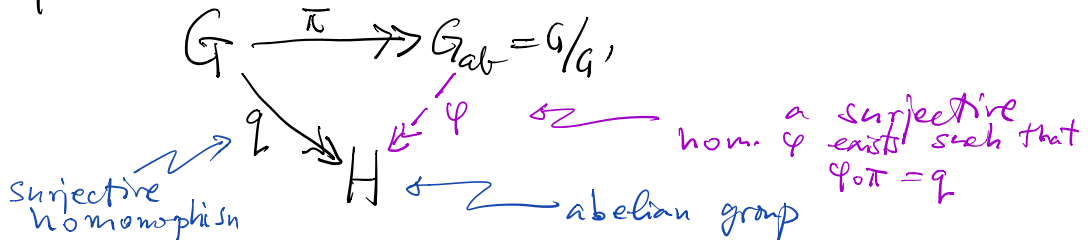
Note Here at the end we used:

(exercise!) Lemma Every factor group of an abelian group is again abelian

Notation / terminology:

$G_{ab} := G/G'$ is called the abelianization of G

By above Prop (part 3), G_{ab} is the largest abelian quotient of G :



Examples ① G simple group $\Rightarrow G_{ab} = \begin{cases} G & \text{if } G \cong \mathbb{Z}_p \\ & (p \text{ prime}) \\ \{e\} & \text{otherwise} \end{cases}$

reason: $G' \triangleleft G \Rightarrow \begin{matrix} G = \{e\} \\ \text{or } G \text{ simple} \end{matrix} \Rightarrow G_{ab} = G \quad \left(\begin{matrix} \text{this happens} \\ \text{when} \\ G = \mathbb{Z}_p \end{matrix} \right)$
 $G' = G \Rightarrow G_{ab} = \{e\}$

eg: $(A_n)_{ab} = \{e\}$ for $n \geq 5$

$(S_3)_{ab} = S_3 / \mathbb{Z}_3 \cong \mathbb{Z}_2$

Prop Every hom $\varphi: G \rightarrow H$ takes G' to H'
 (This implies the derived subgroup is a "fully characteristic subgroup" of G)

Proof $\forall g, h \in G: \varphi(g h g^{-1} h^{-1}) = \varphi(g) \varphi(h) \varphi(g)^{-1} \varphi(h)^{-1} \in H'$

Cor Every hom between two groups induces a hom between their abelianizations:

$$\begin{array}{ccc} G & \xrightarrow{\varphi} & H \\ \pi_G \downarrow & & \downarrow \pi_H \\ G_{ab} & \xrightarrow{\varphi_{ab}} & H_{ab} \end{array} \quad \varphi_{ab} \circ \pi_G = \pi_H \circ \varphi$$

$$\varphi_{ab}(*G') := \varphi(x) \cdot H'$$

Cor If $G \cong H$, then $G_{ab} \cong H_{ab}$:

$$\varphi: G \xrightarrow{\cong} H \Rightarrow \varphi_{ab}: G_{ab} \xrightarrow{\cong} H_{ab}$$